Polymer Processing

Example 1  Dissolve a polymer and apply it as a thin film on a substrate (coating)

Example 2  Melt a polymer and force it into a desired shape (molding)

Injection Molding

Both examples require three ingredients:

1. Fluid Mechanics - What rules govern fluid motion?

2. Rheology - Specific material properties.

3. Processing Equipment - Geometry, rate, pressure, etc.
EXAMPLES OF FLOW

Poiseuille Flow: driven by a pressure difference

\[ p_1 > p_2 \]

velocity profile

Couette Flow: driven by a moving surface

At \( t = 0 \)

At \( t_1 > 0 \)

At \( t_2 > t_1 \)

All velocity in \( x \)-direction

At \( y = 0 \) (bottom, stationary plate) \( \vec{V} = 0 \)

At \( y = h \) (top, moving plate) \( \vec{V} = \vec{V}_0 = V_0 \hat{i} \)

these are "no-slip" boundary conditions

Velocity in fluid \( \vec{V} = V_x \hat{i} + V_y \hat{j} + V_z \hat{k} \)

\( V_y = V_z = 0 \)

\( V_x = V_0 \frac{Y}{h} \)

called SIMPLE SHEAR flow
Stress and Strain in Extension for Elastic Solids

Stretch each from initial length $\ell_0$ to final length $\ell$

$$\frac{F_1}{A_1} = \frac{F_2}{A_2} \quad \therefore F \sim A \quad \text{define stress} \quad \sigma_e \equiv \frac{F}{A} \quad (1)$$

Stretch same bar to different final lengths.

$$F \sim \Delta \ell / \ell_0 \quad \Delta \ell = \ell - \ell_0 \quad (2)$$

define extensional strain $\varepsilon \equiv \Delta \ell / \ell_0$

Hooke’s Law for Elastic Solids:

$$\sigma_e = G_e \varepsilon \quad (3)$$

$G_e$ is the extensional modulus
Stress and Strain in Shear for Hookean (elastic) Solids

Force $F$ applied over area $A$

\[
\frac{F_1}{A_1} = \frac{F_2}{A_2} \quad \therefore F \sim A \quad \text{define shear stress} \quad \sigma_s \equiv \frac{F}{A} \quad (4)
\]

\[
F \sim \frac{\ell}{h}, \text{define shear strain} \gamma \equiv \frac{\ell}{h} \quad (5)
\]

Hooke’s Law in Shear:

\[
\sigma_s = G_s \gamma \quad (6)
\]

$G_s$ is the shear modulus

\[
G_e = 3G_s \quad (7)
\]

Modulus is a material property of a solid.
Mechanical Properties of Newtonian (viscous) Liquids

Stress and strain are defined in the same ways for all materials.

Hooke’s Law does not hold for liquids.

Newtonian liquids have no shape memory.

∴ Stress is not determined by strain.

Stress in a Newtonian liquid is proportional to the rate of strain.

Extension rate $\dot{\varepsilon} \equiv d\varepsilon/dt$

Shear rate $\dot{\gamma} \equiv d\gamma/dt$

Newton’s Law for Viscous Liquids:

$$\sigma_e = \eta_e \dot{\varepsilon} \quad \sigma_s = \eta_s \dot{\gamma}$$

(8)

$\eta_e = $ extensional viscosity

$\eta_s = $ shear viscosity

Trouton’s Rule: $\eta_e = 3\eta_s$

Viscosity is a material property of a liquid.
Stress and Strain for a Polymer Solid

\[ \sigma_e (\varepsilon) \equiv \frac{G_a (\varepsilon)}{\varepsilon} \]

Generalization of the concept of a modulus to the regime of non-linear response.
Stress and Strain for a Polymer Liquid

Apparent Viscosity $\eta_a(\dot{\gamma}) \equiv \frac{\sigma_s(\dot{\gamma})}{\dot{\gamma}}$

Generalization of the concept of a viscosity to the regime of non-linear response.
FIGURE 26. Viscosity versus shear rate for a nearly monodisperse polystyrene at several temperatures. (Reproduced with permission from reference 17. Copyright 1974 John Wiley and Sons, Inc.)

FIGURE 27. Viscosity-shear rate master curve for results shown in Figure 26. The various symbols represent data obtained at different temperatures. (Reproduced with permission from reference 17. Copyright 1974 John Wiley and Sons, Inc.)